

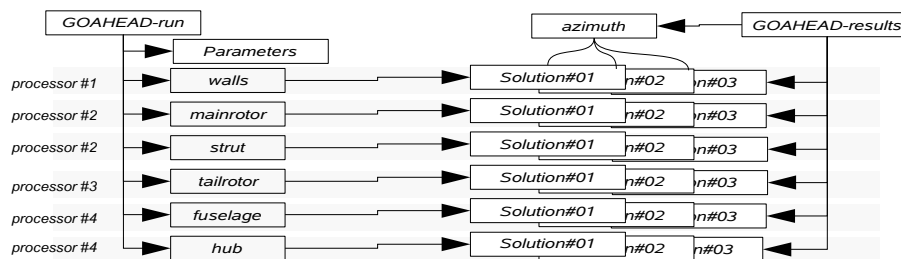


neighbourhood and sets the correct parameters and boundary conditions for the elsA fluid solver [4]. Therefore, a new release of DLR grids is taken into account by parsing again all the information of the CGNS files, no other external data is needed.

### Computation facts

The computation is unsteady and runs on a linux cluster after a distribution of the 145 structured zones using a compliant balancing tool. The CGNS data model is perfectly suited for a parallel computation. When a zone (i.e. block, domain) is separated from the global CGNS tree and sent to a specific processor, it comes with all the solver required data, including connectivities, BCs, solutions... Each run is producing about 1,5Gb of data per degree of rotor azimuth. The computation is restarted every 30 degrees, and thus a post processing has to be performed to build a new restart tree using the solution fields from the previous run: we have to make a loop over solutions becoming the initialization of the next step. We use the CGNS link feature to create an empty skeleton. This skeleton represents the results we would have at the end of one step. When the fluid solver saves the data on disk, one file is saved per processor and the structure of this file is the one expected by the skeleton. Thus, without any other post processing, the user can run visualization tools on the skeleton file now filled. Moreover, the actual solution data is shared between tools through these links, no file duplication is done even if the different pre/post processing tools need different views of the same data.

The data, their relationship and their dependency against the time are shown in the following schema:



### Conclusion

We succeeded in managing large and heterogeneous data using a CGNS data model, including when complex CFD techniques such as chimera are used. This standard data allows interoperability by means of a parsing and understanding of a self-descriptive set of files. An actual GOAHEAD computation has been performed and lessons have been drawn for more interoperability in forthcoming international projects.

### REFERENCES

- [1] "The CGNS System," D. Poirier, S. R. Allmaras, D. R. McCarthy, M. F. Smith, F. Y. Enomoto (AIAA Paper 98-3007).
- [2] "The blind-test activity of the GOAHEAD project", O. Boelens et al, 33<sup>rd</sup> European Rotorcraft Forum, Kazan, September 2007.
- [3] <http://elsa.onera.fr/pyCGNS>
- [4] "The status of elsA CFD software for flow simulation and multi-disciplinary applications." L.Cambier, J.-P. Veullot (AIAA-2008-0664).