

SHEAR CORRECTION OF A THIN PLATE ELEMENT IN ABSOLUTE NODAL COORDINATES

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ABSTRACT

This study is a continuation of an alternative approach to account for transverse shear deformation in the absolute nodal coordinate formulation (ANCF). In the formulation, shear deformation is usually defined by employing the slope vectors in the element transverse direction. This leads to the description of deformation modes that are, in practical problems, associated with high frequencies.

These high frequencies, in turn, complicate the time integration procedure burdening numerical performance. In previous studies [1] and [2], the description of transverse shear deformation is accounted for in a two-dimensional beam element based on the absolute nodal coordinate formulation without the use of transverse slope vectors. In the introduced shear deformable beam element, slope vectors are replaced by vectors that describe the rotation of the beam cross-section. This procedure represents a simple enhancement that does not decrease the accuracy or numerical performance of elements based on the absolute nodal coordinate formulation.

In the current study, the same approach is implemented for a thin rectangular plate element. Numerical results are presented in order to demonstrate the accuracy of the introduced element in static and dynamic cases. The numerical results obtained using the introduced element agree with the results obtained using previously proposed shear deformable plate elements.

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SOME IMPLEMENTATION DETAILS

In the previous study, a two-dimensional beam element was presented. Instead of the conventional set of coordinates for such an element, $\{\mathbf{r}_0^T \quad \mathbf{t}_0^T \quad \mathbf{r}_l^T \quad \mathbf{t}_l^T\}^T$, where \mathbf{r} denotes position vectors and $\mathbf{t} = d\mathbf{r}/ds$ means slope vectors, such an alternative set is used:

$$\mathbf{q} = \{\mathbf{r}_0^T \quad \mathbf{n}_0^T \quad \mathbf{r}_l^T \quad \mathbf{n}_l^T\}^T,$$

where \mathbf{n} denotes normal vector to the cross section. A simple relation holds: $\mathbf{n} = \mathbf{t} + \boldsymbol{\theta}$, where $\boldsymbol{\theta}$ is a shear vector, see Figure 1.

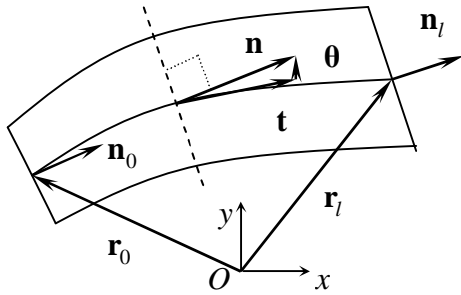


Figure 1. Beam element

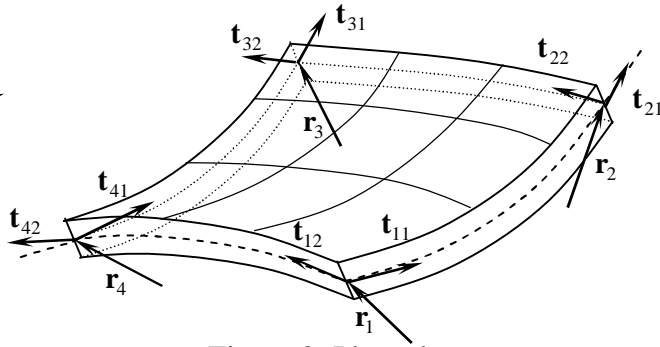


Figure 2. Plate element

The main effort of this paper is the idea of extend this formulation to thin plates. We define the coordinate set for the plate element as follows:

$$\mathbf{q} = \{\mathbf{q}_1^T \quad \mathbf{q}_2^T \quad \mathbf{q}_3^T \quad \mathbf{q}_4^T\}^T$$

where each node of the plate introduces such nodal vectors following the idea for the beam element above:

$$\mathbf{q}_k = \{\mathbf{r}_k^T \quad \mathbf{n}_{k1}^T \quad \mathbf{n}_{k2}^T\}^T,$$

instead of conventional set of nodal vectors $\{\mathbf{r}_k^T \quad \mathbf{t}_{k1}^T \quad \mathbf{t}_{k2}^T\}^T$ shown in Figure 2. Vectors $\mathbf{n}_{k1}, \mathbf{n}_{k2}$ are not presented in the figure.

REFERENCES

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