

## 3D-Continuum Theory of Dislocations: Numerical Implementation and Application

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### ABSTRACT

The growing demand for physically motivated continuum theories of plasticity led to an increased effort on continuum descriptions based on dislocations. For simplified systems of straight parallel edge dislocations in a single slip configuration a quasi two-dimensional theory is available, derived by methods of statistical mechanics for interacting particle systems [1].

However, earlier attempts to transfer this method to three-dimensional systems of curved dislocations failed. This was due to the inability of the classical dislocation density measures to reflect all dislocations as line like objects. The reason is that the Kröner tensor  $\alpha$  [2], as a measure for geometrically necessary dislocations (GND) comprises only a fraction of all dislocations, while the scalar density of statistically stored dislocations (SSD) contains no directional information.

This deficiency was remedied by a recently introduced extended continuum theory of dislocations [3]. This theory utilizes a generalized definition of the dislocation density tensor, the so-called dislocation density tensor of second order,  $\alpha^{II}$ . Within this tensor all dislocations appear as line like objects; the distinction between GND and SSD becomes dispensable. Therefore this theory allows for a *meaningful* averaging process.

We study the extended continuum theory for the 2-dimensional special case of a single glide system. For this special case the tensorial evolution equation of the dislocation density tensor  $\alpha^{II}$  can be reformulated into two evolution equations for the scalar-valued fields *scalar dislocation density*  $\rho$  and *curvature*  $k$ . These equations were numerically implemented by use of a finite difference scheme for the spatial derivatives and a forward Euler time integration scheme.

We numerically validate the theory by showing that these continuum evolution equations can handle the kinematic evolution of discrete dislocations. The constituents of these evolution equations and their implications for the numerical implementation will be explored by numerical examples. We show, that our method can treat various kinds of dislocation distributions - density fields as well as quasi-discrete dislocations.

We derive the set-up for the numerical treatment of impenetrable boundary conditions. The effect of dislocation pile-ups at impenetrable boundaries is studied and compared to alternative approaches (e.g. [4]).

Furthermore, we show the necessary steps for embedding the evolution equations (on the meso-scale) into a crystal plasticity context (on the micro-scale). This allows for computation of stress field evolution and dislocation patterning, e.g. for composite materials as shown in [5] and [6].

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