SOFT COMPUTING METHODS IN COMPUTATIONAL GRIDS

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ABSTRACT

The paper is devoted to soft computing methods in computational grids. The computational grids provide sophisticated and user friendly environment for performing time consuming computations. The grids are build on top of cluster, supercomputers and networks connecting resources. The grid middleware plays important role connecting resources with different hardware, operating systems, queuing systems. The use of grid middleware such as Unicore[5], Alchemi[1], gives oportunity to use distributed heterogenous resources by comunicationg with standarized grid middleware. The soft computing methods applied to optimization and aproximation problems in mechanics are considered. The evolutionary algorithms[4], artificial immune systems[2], particle swarm optimization[3] and artificial neural networks are considered. The parallelization of these algorithms allows efficient utilization of grids resources. The objective function in optimization problems is computed using the finite element method.

The full paper contains examples of optimization and aproximation using parallel soft computing algorithms, speedup measurements and results comparison. The optimization in contact problem is considered as one of the examples. The contact between seal and rigid body is considered. The objective function depends on the contact status – part of the flexible body should be touching rigid one and area of the flexible structure. The fitness function is expressed as:

$$\min_{\mathbf{ch}} F(\mathbf{ch}); \quad F(\mathbf{ch}) = \int_{\Omega} d\Omega - w_c \int_{\Gamma_c} d\Gamma_c$$
(1)

where: ch - is a chromosome, Ω - domain of the flexible body, Γ_c - flexible body boundary in contact with rigid body, w_c - scaling coefficient in length units. The constraints on maximum equivalent stresses value are imposed. The scaling coefficient is used to obtain balance between two parts of the fitness function. The shape of the flexible body is defined by the NURBS curve (Fig.1a). The design variables are coordinates of control polygon points of the NURBS curve. The genes contain control polygon points coordinates. The geometry and boundary condition for test problem are shown in Fig. 1a. The flexible

body is constrained on bottom surface. The prescribed displacements of the rigid body are shown by the arrow. The flexible body is described using two NURBS curves, each with 10 moving control points. Total number of genes is 40. The Fig. 1b presents best found shape of the seal.



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